

# Negative feedback

# 2

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## 1. Introduction

This exercise allows you to measure and compare the properties of an amplifier operating in the following configurations (see Fig. 21):

- A – amplifier with open feedback loop (i.e. without feedback),
- B – amplifier with closed feedback loop of type (1),
- C – amplifier with closed feedback loop of type (2).

The tested circuit is a two-stage amplifier composed of two bipolar transistors operating in common emitter (CE) configuration. This amplifier is covered by a negative voltage-series feedback.

In this exercise, you should measure the following amplifier's parameters: gain in the centre of the passband, input and output resistance, low and high 3-decibel (3-dB) frequency. Particular configurations (A, B or C) are selected by means of rotary switch (Fig. 21). For independence of parameters of measuring instruments and quality of connections, the amplifier has built-in unity-gain buffers at both the input and the output.

**Before exercise, you should be familiar with the course (basic information is presented in this paper). Teacher is obliged to examine the preparation for the exercise.**

## 2. Measurements

For each of the circuits A, B, and C, **you should**:

- a) Measure the **low and high 3-dB cutoff frequencies,  $f_{L3dB}$  and  $f_{H3dB}$** . The measurement should be performed as follows:
  - Set the input frequency of 18 kHz and set the input voltage ( $v_s$ ) for the circuit A  $\approx 1$  mV<sub>RMS</sub>, for B  $\approx 10$  mV<sub>RMS</sub>, and for C  $\approx 5$  mV<sub>RMS</sub>. Next, you must adjust the input voltage  $v_s$  so that the output voltage  $v_o$  is equal to 300 mV<sub>RMS</sub>.
  - Increase the generator frequency until the output voltage  $v_o$  drops to  $300 \text{ mV}_{RMS}/\sqrt{2} \approx 212 \text{ mV}_{RMS}$  — the resulting frequency is the high 3-dB cutoff frequency (Warning: During the frequency change, you must keep a constant input rms voltage!).
  - Decrease the generator frequency until the output voltage  $v_o$  drops to  $300 \text{ mV}_{RMS}/\sqrt{2} \approx 212 \text{ mV}_{RMS}$  — the resulting frequency is the low 3-dB cutoff frequency (Warning: During the frequency change, you must keep a constant input rms voltage!).
- b) Calculate a **center frequency  $f_0$**  from the formula  $f_0 = \sqrt{f_{L3dB} \cdot f_{H3dB}}$  and measure the **amplifier gain** ( $K_u = v_o/v_s$ ) at this center frequency.
- c) Measure an **input resistance  $R_{in}$** . Set the input frequency of 18kHz and the amplitude as in the point a). Input resistance is measured using additional resistor  $R_S'$  connected in series with the internal resistance  $R_S$  of the generator. Press the button  $R_{in}$  and note the output voltage. For more details, see the description in section 5.
- d) Measure an **output resistance  $R_{out}$** . Set the input frequency of 18kHz and the amplitude as in the point a). Output resistance is measured using additional resistor  $R_L'$  connected in parallel with the load resistance  $R_L$  of the amplifier. Press the button  $R_{out}$  and note the output voltage. For more details, see the description in section 6.
- e) Measure **nonlinear distortions  $h$** . Set the input frequency of 18kHz and set the amplitude as in the point a).

- f) Measure the **amplitude characteristic** by a point-by-point method.

## 3. Results elaboration

Plot the measured amplitude characteristics on separate graphs. The vertical axis should be "Gain" expressed in decibels, i.e.,  $20\log|K_u|$ . The horizontal axis (i.e., frequency) should be logarithmic.

Calculate (on the basis of formulas included in the protocol) for circuits A, B, and C, the following quantities:

- operating points of transistors,
- amplifier gain  $K_u$ ,
- input and output resistances of the amplifier.

Compare the above theoretical results with the measured results. Comment compliance of theoretical calculations with the measurements.

Include your conclusions.

## 4. Theory

### 4.1 Properties of negative feedback

When applied to an amplifier, a negative feedback causes:

- reduction of gain sensitivity to temperature, supply, etc.,
- modification of the input and output resistance,
- reduction of nonlinear distortion (in most cases),
- widening of the pass band (increasing the bandwidth).

Disadvantages of negative feedback are:

- it reduces an amplifier gain,
- it may cause instability of an amplifier.

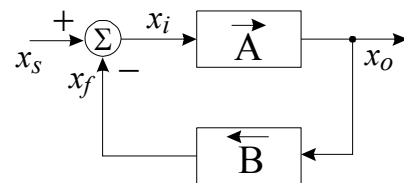


Fig. 1. Block diagram of an ideal feedback loop.

The diagram of an ideal feedback is shown in Fig. 1. The gain of the circuit with closed feedback loop is:

$$A_f \equiv \frac{x_o}{x_s} = \frac{x_o}{x_i + x_f} = \frac{Ax_i}{x_i + ABx_i} = \frac{A}{1 + AB}$$

- $AB$  - loop gain
- $1+AB=F$  - amount of feedback

The impact of negative feedback on the frequency response of a linear amplifier A will be analyzed as follows. Let's assume that the frequency response of an amplifier without feedback is:

$$A(s) = \frac{A_M}{(1 + \omega_L/s)(1 + s/\omega_H)}$$

The amplifier gain for medium pulsations ( $\omega_L \ll \omega \ll \omega_H$ ) is  $A_M$ , and its bandwidth is limited by two border pulsations,  $\omega_L$  – low pulsation and  $\omega_H$  – high pulsation. Furthermore, we assume that the characteristic of the feedback network B is constant and independent of frequency. After closing the feedback loop we get:

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- the gain within bandwidth (i.e., the gain at center

$$\text{frequency): } A_f = \frac{A_M}{1 + A_M B} = \frac{A_M}{F},$$

- low 3-dB pulsation:  $\omega_{Lf} = \frac{\omega_L}{(1 + A_M B)} = \frac{\omega_L}{F},$

- high 3-dB pulsation:  $\omega_{Hf} = \omega_H (1 + A_M B) = \omega_H F.$

As follows from the above relationships, the negative feedback expands the amplifier bandwidth. For the amplifier described by one-pole transfer function, its unity-gain frequency (the product of the gain and bandwidth of the amplifier) remains unchanged.

A valuable feature of the feedback is to reduce the gain sensitivity to changes in supply, temperature etc.

The gain sensitivity to variation in supply voltage is given by the formula:

$$S_{Uz}^A = \frac{\frac{dA}{A}}{\frac{dUz}{Uz}} = \frac{dA}{dUz} \frac{Uz}{A}$$

or for finite increments by the formula:  $S_{Uz}^A = \frac{\Delta A}{\Delta Uz} \frac{Uz}{A}$

An important parameter of the whole system from Fig. 1 is its gain sensitivity to variation in the gain of a subsystem A. This sensitivity is expressed by the formula:

$$S_A^{A_f} = \frac{\frac{\Delta A_f}{A_f}}{\frac{\Delta A}{A}} = \frac{1}{1 + AB} = \frac{1}{F}$$

or by the formula (useful for measurements):

$$S_A^{A_f} = \frac{S_{Uz}^{A_f}}{S_{Uz}^A}$$

because  $\frac{\Delta A_f}{A_f} = S_{Uz}^{A_f} \frac{\Delta Uz}{Uz}$      $\frac{\Delta A}{A} = S_{Uz}^A \frac{\Delta Uz}{Uz}$

In this exercise, we use an amplifier with a voltage-series negative feedback. Hence, only this kind of feedback will be discussed in the following text. The topology of this feedback is depicted in Fig. 2. The output voltage  $v_o$  is fed (through a two-port feedback network) to the input, in series with the source  $v_s$ . In the theoretical analysis, we assume:

- a) the circuits A and B are unilateral,
- b) the circuit A is a voltage amplifier with a gain  $v_o/v_i = A$ , with an input resistance  $R_i$  and output resistance  $R_o$ ,
- c) the circuit B has a voltage transfer function  $B = v_f/v_o$ , and it doesn't load the circuit A (i.e., doesn't change the gain of circuit A).

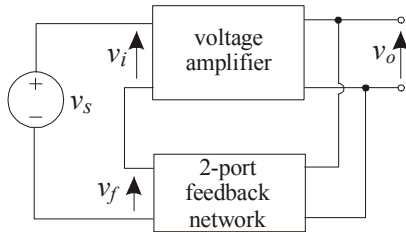


Fig. 2. Topology of voltage-series negative feedback.

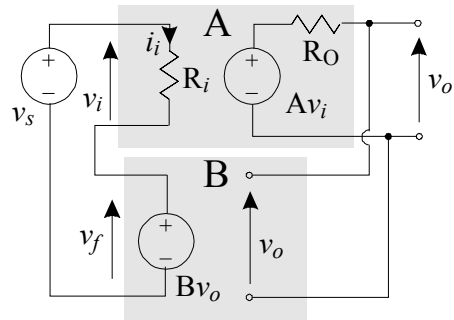


Fig. 3. Model of an amplifier with voltage-series negative feedback.

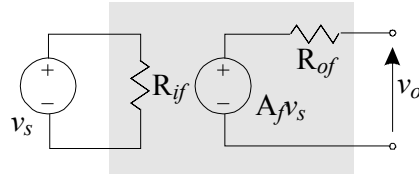


Fig. 4. Model of the main amplifier.

The circuit gain is:

$$A_f = \frac{v_o}{v_s} = \frac{A}{1 + AB}$$

The input resistance is:

$$R_{if} = R_i (1 + AB)$$

The output resistance is:

$$R_{of} = \frac{R_o}{(1 + AB)}$$

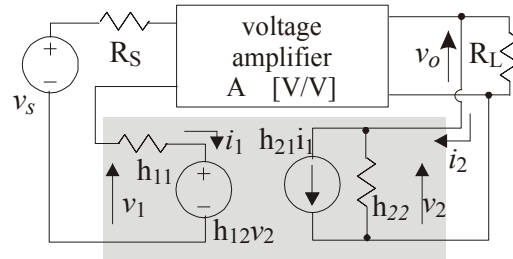


Fig. 5. Model of a real amplifier with voltage-series negative feedback.

In real implementations, two-port feedback network is mostly a passive circuit. Therefore, we can assume:

- the reverse transfer function of a two-port feedback network is negligibly small compared to the gain of an active circuit A (i.e.,  $h_{21}=0$ ),
- the forward transfer function of two-port feedback network is  $B=h_{12}=v_1/v_o$  at  $i_1=0$ .

The ideal two-port network A should be complemented with additional elements, that is, the resistances contributed by the feedback network, i.e., elements  $h_{11}$  and  $1/h_{22}$ . The resistance  $R_s$  of an input source and the load resistance  $R_L$ , should also be taken into account ( $R_s$  and  $R_L$  should be contributed to A). As a result, the diagram from Fig. 5 is converted to the diagram in Fig. 6, where the two-port network A is replaced by a modified two-port network A'. We can see, that the elements  $h_{11}$ ,  $1/h_{22}$ ,  $R_s$  and  $R_L$  are included in the network A'.

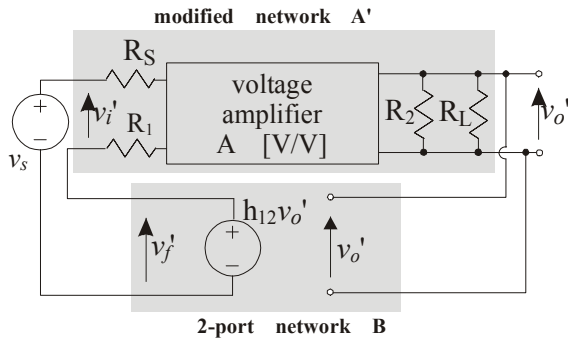


Fig. 6. The modified circuit.

As a summary, the entire process of the network transformation is depicted in Fig. 6.

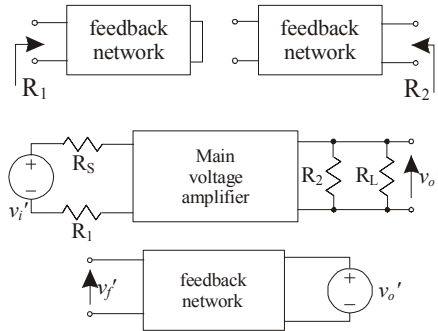


Fig. 6. Summary of transformations.

$$A' = \frac{v_o'}{v_i'} \quad B = \frac{v_f'}{v_o'} \quad A_f = \frac{v_o}{v_s} = \frac{A'}{1 + A'B}$$

**4.2. Small-signal analysis of a two-stage amplifier with voltage-series negative feedback.**

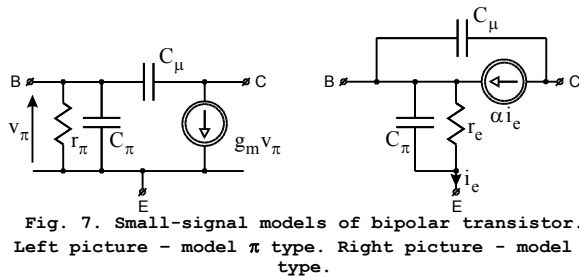


Fig. 7. Small-signal models of bipolar transistor. Left picture - model  $\pi$  type. Right picture - model T type.

Parameters of the transistor models from Fig. 7 are:

$$g_m = \frac{I_C}{V_T}, \quad r_\pi = \frac{\beta}{g_m}, \quad \alpha = \frac{\beta}{\beta + 1}, \quad r_e = \frac{r_\pi}{\beta + 1},$$

$$C_\pi = \frac{g_m}{2\pi \cdot f_T} - C_\mu$$

**4.2.1 Operating point**

Operating points of the transistors can be derived under the following assumptions: DC base current  $I_B$  is very small and can be omitted (i.e.,  $I_B = 0$ ), base-emitter voltage is constant and equal to 0.7 V, thermal voltage is  $V_T = 25$  mV. The operating point is the same for the amplifier without and with the feedback.

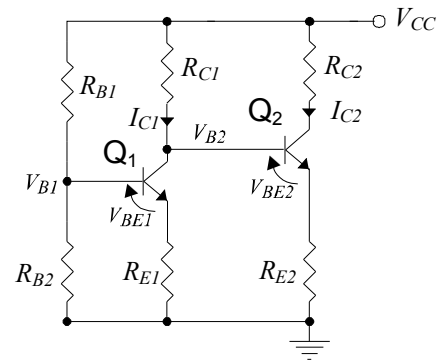


Fig. 9. Amplifier diagram for calculating of an operating point.

DC currents and voltages in the amplifier network (Fig. 9) can be calculated using the following equations:

$$V_{B1} \approx V_{CC} \frac{R_{B2}}{R_{B1} + R_{B2}} \tag{1}$$

$$I_{C1} \approx I_{E1} = \frac{V_{B1} - 0,7V}{R_{E1}} \tag{2}$$

$$V_{CE1} = V_{CC} - (R_{C1} + R_{E1})I_{C1} \tag{3}$$

$$V_{B2} = V_{CC} - R_{C1}I_{C1} \tag{4}$$

$$I_{C2} \approx I_{E2} = \frac{V_{B2} - 0,7V}{R_{E2}} \tag{5}$$

$$V_{CE2} = V_{CC} - (R_{C2} + R_{E2})I_{C2} \tag{6}$$

**4.3. Small-signal analysis of two-stage amplifier with an open feedback loop (configuration A).**

Analysis for middle frequencies (i.e., near centre of bandwidth)  
A small-signal diagram of the amplifier from Fig. 9 is depicted in Fig. 10. The diagram is created assuming the amplifier operates in middle frequency range. In this case, all coupling capacitors are assumed to be short-circuits for AC signals, all parasitic capacitances of transistors are open, and a supply line is assumed to be grounded.

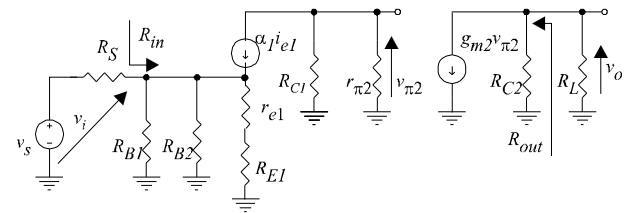


Fig. 10. Small-signal diagram of an amplifier for middle frequencies.

The input and output resistances of the considered amplifier are as follows:

$$R_{in} = R_{B1} \parallel R_{B2} \parallel (r_{e1} + R_{E1})(\beta + 1) \tag{7}$$

$$R_{out} = R_{C2} \tag{8}$$

and the amplifier gain is:

$$\frac{v_o}{v_s} = \frac{v_o}{v_{\pi 2}} \frac{v_{\pi 2}}{i_{e1}} \frac{i_{e1}}{v_i} \frac{v_i}{v_s} \tag{9}$$

$$\frac{v_o}{v_s} = g_{m2} (R_{C2} \parallel R_L) \frac{\alpha (R_{C1} \parallel r_{\pi 2})}{r_{e1} + R_{E1}} \frac{R_{in}}{R_{in} + R_S} \tag{10}$$

Analysis for high frequencies (i.e., near a high 3-dB frequency)

A small-signal diagram of the amplifier of Fig. 9 is depicted in Fig. 11. The diagram is created assuming that the amplifier operates in high frequency range, i.e., near high 3-dB frequency. The high 3-dB frequency can be derived using a time-constant method. The time constants result from parasitic capacitances and resistances seen from the capacitors' terminals.

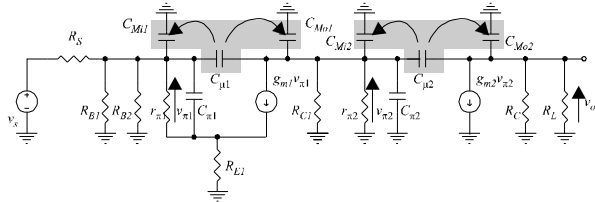


Fig. 11. Small-signal diagram for calculating a high 3-dB frequency.

Using Miller's theorem, a parasitic "floating" capacitance  $C_{\mu}$  of transistor can be transferred to two "grounded" capacitances  $C_{Mi}$  and  $C_{Mo}$ :

$$C_{Mi1} = C_{\mu1} \left( 1 + \frac{r_{\pi1} g_{m1} (R_{C1} \parallel r_{\pi2})}{r_{\pi1} + R_{E1} (\beta_1 + 1)} \right) = \quad (11)$$

$$= C_{\mu1} \left( 1 + \frac{R_{C1} \parallel r_{\pi2}}{r_{e1} + R_{E1}} \right)$$

$$C_{Mo1} = C_{\mu1} \left( 1 + \frac{r_{e1} + R_{E1}}{R_{C1} \parallel r_{\pi2}} \right) \quad (12)$$

$$C_{Mi2} = C_{\mu2} (1 + g_{m2} R_{C2} \parallel R_L) \quad (13)$$

$$C_{Mo2} = C_{\mu2} \left( 1 + \frac{1}{g_{m2} R_{C2} \parallel R_L} \right) \quad (14)$$

Using equations (11)-(14), the time constants related to particular capacitances can be easily derived:

$$\tau_{H1} = C_{Mi1} \cdot (R_{B1} \parallel R_{B2} \parallel R_S \parallel (r_{e1} + R_{E1}) (\beta_1 + 1)) \quad (15)$$

$$\tau_{H2} = C_{\pi1} \left( r_{\pi1} \parallel \frac{R_S \parallel R_{B1} \parallel R_{B2} + R_{E1}}{1 + g_{m1} R_{E1}} \right) \quad (16)$$

$$\tau_{H3} = (C_{Mo1} + C_{Mi2} + C_{\pi2}) \cdot (R_{C1} \parallel r_{\pi2}) \quad (17)$$

$$\tau_{H4} = C_{Mo2} \cdot (R_{C2} \parallel R_L) \quad (18)$$

Approximate value of a high 3-dB frequency can be expressed by the formula:

$$f_{H3dB} \approx \frac{1}{2\pi \cdot (\tau_{H1} + \tau_{H2} + \tau_{H3} + \tau_{H4})} \quad (19)$$

or by more precise formula:

$$f_{H3dB} \approx \frac{1}{2\pi \cdot \sqrt{\tau_{H1}^2 + \tau_{H2}^2 + \tau_{H3}^2 + \tau_{H4}^2}} \quad (20)$$

**Analysis for low frequencies (i.e., near a low 3-dB frequency)**

A small-signal diagram of the amplifier of Fig. 9 is depicted in Fig. 12. The diagram is created assuming that the amplifier operates in low frequency range, i.e., near low 3-dB frequency. The low 3-dB frequency can be derived using a time-constant method. Contrary to the previous analysis, the time constants result from coupling capacitances and resistances seen from the capacitors terminals (when calculating the time constant for a particular capacitance, the remaining capacitances should be treated as a short-circuit). Parasitic capacitances are treated as open-circuits.

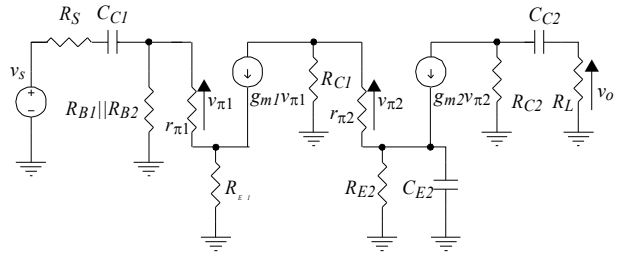


Fig. 12. Small-signal diagram of an amplifier for low frequencies.

The particular time constants are:

$$\tau_{L1} = C_{C1} (R_S + R_{B1} \parallel R_{B2} \parallel ((\beta_1 + 1) R_{E1} + r_{\pi1})) \quad (21)$$

$$\tau_{L2} = C_{E2} \left( R_{E2} \parallel \frac{r_{\pi2} + R_{C1}}{\beta_2 + 1} \right) \quad (22)$$

$$\tau_{L3} = C_{C2} (R_{C2} + R_L) \quad (23)$$

Approximate value of a low 3-dB frequency can be expressed by the formula:

$$f_{L3dB} \approx \frac{1}{2\pi} \left( \frac{1}{\tau_{L1}} + \frac{1}{\tau_{L2}} + \frac{1}{\tau_{L3}} \right) \quad (24)$$

or by more precise formula:

$$f_{L3dB} \approx \frac{1}{2\pi} \sqrt{\frac{1}{\tau_{L1}^2} + \frac{1}{\tau_{L2}^2} + \frac{1}{\tau_{L3}^2}} \quad (25)$$

**4.4. Small-signal analysis of two-stage amplifier with closed feedback loop (configurations B and C).**

The main amplifier (from Fig. 9) with closed feedback loop is depicted in Fig. 13. The elements  $C_F$  and  $R_F$  are added to the main amplifier. Now, the resistor  $R_E$  and the additional elements  $C_F$ ,  $R_F$  form the two-port feedback network. The feedback loop passes only AC signals, because the capacitor  $C_F$  blocks a DC signal. The capacitance  $C_F$  is large enough to be omitted in further small-signal analysis (i.e.,  $C_F$  can be treated as a short-circuit).

The points (cross symbols) of interrupting the feedback loop in order to extract the main amplifier A and a feedback network B are marked in Fig. 13.

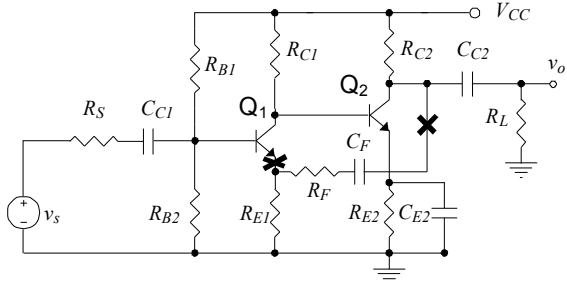


Fig. 13. Diagram of an amplifier with the feedback loop. On the picture are marked spots interrupt the feedback loop to extract the main amplifier A and a feedback network B.

Assuming the operations for middle frequencies (then the coupling capacitors  $C_{C1}$ ,  $C_{E2}$ ,  $C_{C2}$  and  $C_F$  are short-circuits) the diagram in Fig. 13 can be simplified as shown in Fig. 14.

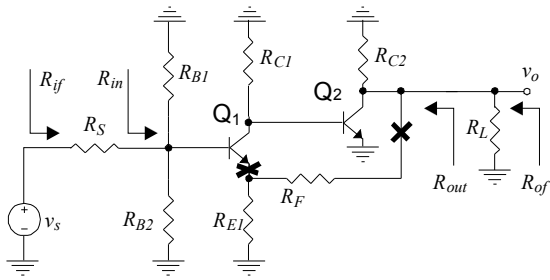


Fig. 14. Diagram of an amplifier with the feedback loop for middle frequencies.

The circuits A and B are shown in Fig. 15 and Fig. 16, respectively.

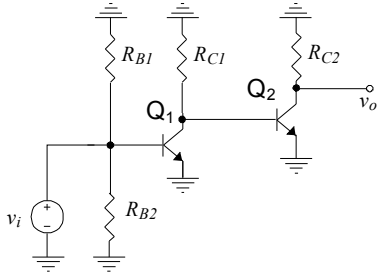


Fig. 15. The main amplifier - circuit A.

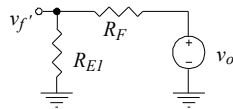


Fig. 16. Two-port feedback network - circuit B.

$$B = \frac{v_f'}{v_o} = \frac{R_{E1}}{R_{E1} + R_F} \quad (26)$$

$$R_1 = h_{11} = R_{E1} \parallel R_F \quad (27)$$

$$R_2 = \frac{1}{h_{22}} = R_{E1} + R_F \quad (28)$$

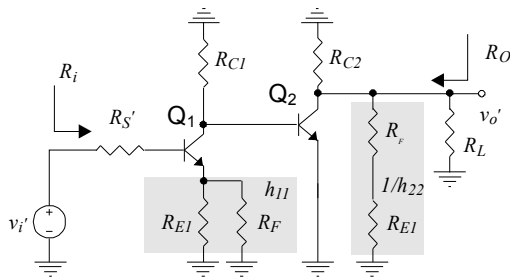


Fig. 17. The modified circuit A'.

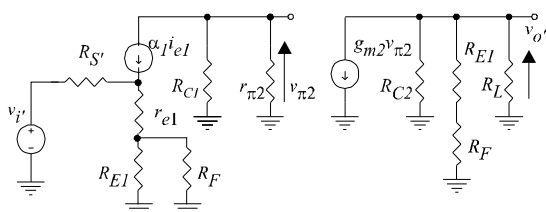


Fig. 18. Small-signal model of circuit A'.

Because the resistors  $R_{B1}$  and  $R_{B2}$  are not a part of the feedback loop, these elements can be included in an equivalent resistance of Thevenin source:

$$R_{S'} = R_{B1} \parallel R_{B2} \parallel R_S \quad (29)$$

The gain of the modified circuit A' is expressed by the formula:

$$A' = \frac{v_o'}{v_i'} = g_{m2} (R_{C2} \parallel R_L \parallel (R_{E1} + R_F)) \frac{\alpha_1 (R_{C1} \parallel r_{\pi 2})}{r_{e1} + R_{E1} \parallel R_F} \cdot \frac{(r_{e1} + R_{E1} \parallel R_F)(\beta_1 + 1)}{(r_{e1} + R_{E1} \parallel R_F)(\beta_1 + 1) + R_{S'}} \quad (30)$$

Hence, the gain of the circuit with closed feedback loop is:

$$A_f = \frac{v_o}{v_s} = \frac{A'}{1 + A'B} \quad (31)$$

The input resistance of the modified circuit A' is:

$$R_i = R_{S'} + (\beta_1 + 1)(r_{e1} + R_{E1} \parallel R_F) \quad (32)$$

The input resistance of the circuit with closed feedback loop is:

$$R_{if} = R_i (1 + A'B) \quad (33)$$

The input resistance of the real circuit with the feedback is:

$$R_{in} = (R_{if} - R_{S'}) \parallel R_{B1} \parallel R_{B2} \quad (34)$$

The output resistance of the modified circuit A' is:

$$R_O = R_{C2} \parallel R_L \parallel (R_{E1} + R_F) \quad (35)$$

The output resistance of the circuit with feedback is:

$$R_{of} = \frac{R_O}{(1 + A'B)} \quad (36)$$

The output resistance of the real circuit with the feedback is:

$$\frac{1}{R_{of}} = \frac{1}{R_{out}} + \frac{1}{R_L} \Rightarrow R_{out} = \frac{R_{of} R_L}{R_L - R_{of}} \quad (37)$$

## 5. Measurement of the input resistance

The input resistance is measured using an additional resistor  $R_{S'}$  connected in series with the internal resistance  $R_S$  of the generator. The resistor  $R_{S'}$  is "activated" by a button on the front panel (the button is marked as  $R_{in}$ ). During normal operation, the button is not pressed and the resistor  $R_{S'}$  is short-circuited (i.e., the  $R_{S'}$  is "inactive"). After pressing the button, the resistor  $R_{S'}$  is connected in series with  $R_S$ , which reduces the amplifier's gain.

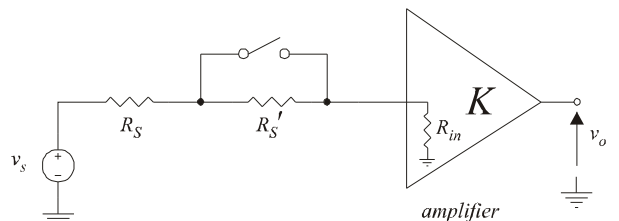


Fig. 19. The method of measuring the input resistance of the amplifier.

Let's denote the output voltage, when  $R_{S'}$  is short circuited (the button is not pressed), as  $v_o$ . Furthermore, let's denote the output voltage, when  $R_{S'}$  is not short circuited (the button is pressed), as  $v_o'$ . We can write the following equations:

$$v_o = K \cdot \frac{R_{in}}{R_{in} + R_S} \cdot v_s \quad (38)$$

$$v_o' = K \cdot \frac{R_{in}}{R_{in} + R_S + R_{S'}} \cdot v_s \quad (39)$$

$$\frac{v_0}{v_0'} = \frac{R_{in} + R_S + R_S'}{R_{in} + R_S} \quad (40)$$

$$R_{in} = \frac{v_0'}{v_0 - v_0'} \cdot R_S' - R_S \quad (41)$$

### 6. Measurement of the output resistance

The output resistance is measured using an additional resistor  $R_L'$  connected in parallel with the load resistance  $R_L$  of the amplifier. The resistor  $R_L'$  is "activated" by a button on the front panel (the button is marked as  $R_{out}$ ). During normal operation, the button is not pressed and the resistor  $R_L'$  is unconnected (i.e., the  $R_L'$  is "inactive"). After pressing the button, the resistor  $R_L'$  is connected in parallel with  $R_L$ , which reduces the amplifier gain.

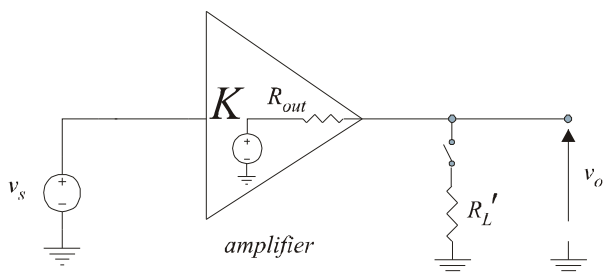


Fig. 20. The method of measuring the output resistance of the amplifier.

Let's denote the output voltage, when  $R_L'$  is unconnected (the button is not pressed), as  $v_0$ . Furthermore, let's denote the output voltage, when  $R_L'$  is connected (the button is pressed), as  $v_0'$ . We can write the following equations:

$$v_0 = K \cdot \frac{R_L}{R_L + R_{out}} \cdot v_s \quad (42)$$

$$v_0' = K \cdot \frac{R_L \parallel R_L'}{R_L \parallel R_L' + R_{out}} \cdot v_s \quad (43)$$

$$\frac{v_0'(R_L \parallel R_L' + R_{out})}{R_L \parallel R_L'} = \frac{v_0(R_L + R_{out})}{R_L} \quad (4)$$

$$R_{out} = \frac{R_L \cdot R_L'}{\frac{R_L \cdot v_0'}{v_0 - v_0'} - R_L'} \quad (44)$$

### 7. Elements parameters

Parameter	Value
$\beta$ for $Q_1$ and $Q_2$	200
$C_{it}$ for $Q_1$ and $Q_2$	4.5 pF
$f_T$ for $Q_1$ and $Q_2$	150 MHz
$V_{CC}$	+12 V
$R_{B1}$	51 k $\Omega$
$R_{B2}$	6.2 k $\Omega$
$R_{C1}$	8.2 k $\Omega$
$R_{E1}$	560 $\Omega$
$R_{C2}$	2.2 k $\Omega$
$R_{E2}$	1.2 k $\Omega$
$R_L$	5.1 k $\Omega$
$R_{FB}$	18 k $\Omega$
$R_{FC}$	36 k $\Omega$
$R_{S'}$	2 k $\Omega$

$R_L', R_S$	1 k $\Omega$
$C_{C1}, C_{C2}$	6.8 $\mu$ F
$C_{E2}$	680 nF

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