

# STM32 Ecosystem workshop

T.O.M.A.S Team



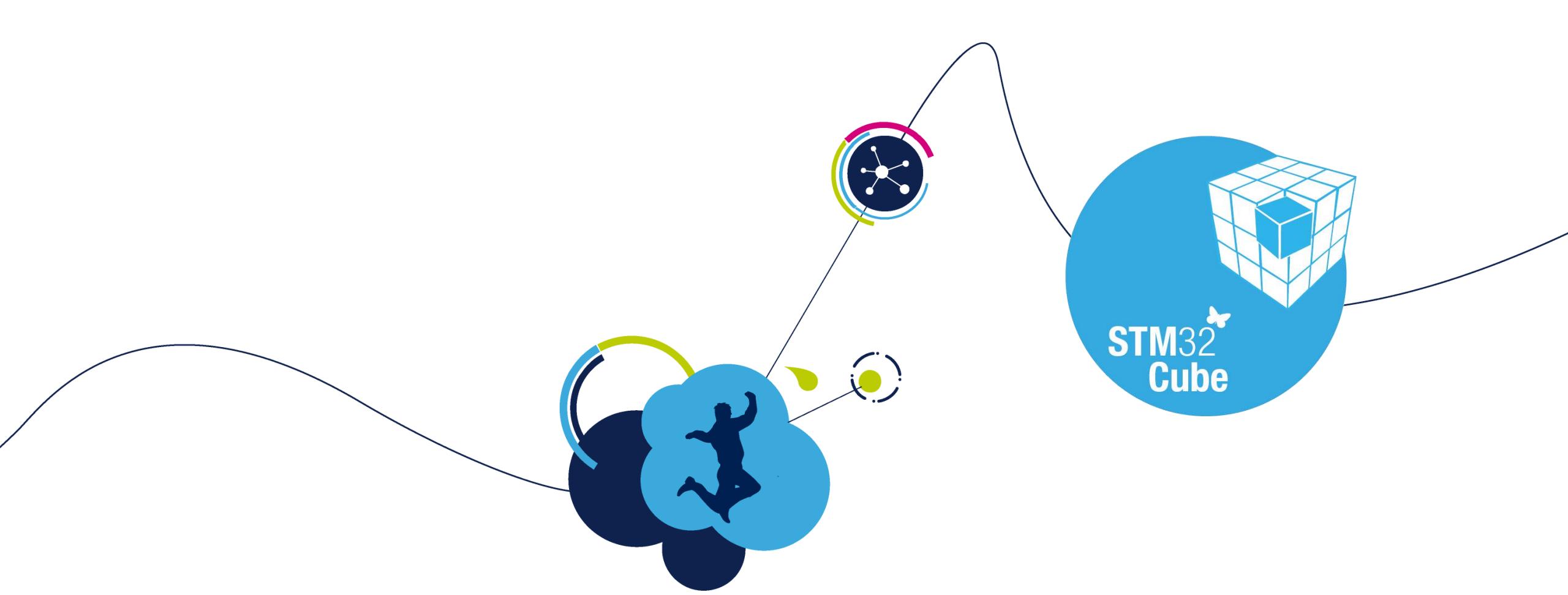


- Before adding a new code let's go with some theory explaining the Cube Library structure and what is generated by STM32CubeMX

# Goal of this part

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- ❑ Understand the structure of the code generated by STM32CubeMX
- ❑ Know the role of the library files
- ❑ Know the role of the functions executed before main
- ❑ Understand interrupt handling process



# STM32CubeMX generated code



# STM32CubeMX generated code code structure, main operations after the reset

```
SystemInit();  
main()  
{  
    HAL_Init()  
    {  
        HAL_MspInit();  
    }  
  
    SystemClockConfig();  
  
    MX_PPP_Init()  
    {  
        HAL_PPP_Init()  
        {  
            HAL_PPP_MspInit();  
        }  
    }  
  
    HAL_PPP_Action();  
    while(1);  
}
```

Located in: system\_stm3214xx.c

Called from: startup\_stm3214xx.s (reset vector before main())

It performs the following operations:

- Enables Floating Point Unit (**FPU**) inside the core
- Resets the **Clock Configuration** to the default reset state
- Disables all **Interrupts**
- Configures **Vector Table** location and its offset

It does NOT configure the clock system (as it was done in Standard Peripherals Library (SPL))



```
SystemInit();  
main()  
{  
    HAL_Init()  
    {  
        HAL_MspInit();  
    }  
  
    SystemClockConfig();  
  
    MX_PPP_Init()  
    {  
        HAL_PPP_Init()  
        {  
            HAL_PPP_MspInit();  
        }  
    }  
  
    HAL_PPP_Action();  
    while(1);  
}
```

# STM32CubeMX generated code code structure, main operations after the reset

Located in: stm3214xx\_hal.c  
Called from: main.c

It performs the following operations:

- Configures **FLASH accelerator**
- Configures **NVIC priority** (group and sub-priorities split)
- Configures **SysTick** for 1ms tick (based on HSI clock)
- Initializes **Low-level hardware** selected in STM32CubeMX (call to HAL\_MspInit() function)



```
SystemInit();  
main()  
{  
    HAL_Init()  
    {  
        HAL_MspInit();  
    }  
  
    SystemClockConfig();  
  
    MX_PPP_Init()  
    {  
        HAL_PPP_Init()  
        {  
            HAL_PPP_MspInit();  
        }  
    }  
  
    HAL_PPP_Action();  
    while(1);  
}
```

# STM32CubeMX generated code code structure, main operations after the reset

Located in: stm3214xx\_hal\_msp.c  
Called from: stm3214xx\_hal.c

It performs the following operations:

- Configures **Interrupts Priorities**  
(for each peripheral selected in STM32CubeMX)



# STM32CubeMX generated code

## code structure, main operations after the reset

```
SystemInit();  
main()  
{  
    HAL_Init()  
    {  
        HAL_MspInit();  
    }  
  
    SystemClockConfig();  
  
    MX_PPP_Init()  
    {  
        HAL_PPP_Init()  
        {  
            HAL_PPP_MspInit();  
        }  
    }  
  
    HAL_PPP_Action();  
    while(1);  
}
```

Located in: main.c

Called from: main.c

It performs the following operations:

- Configures **System & Buses clocks**  
(based on STM32CubeMX clock settings)



# STM32CubeMX generated code code structure, main operations after the reset

```
SystemInit();  
main()  
{  
    HAL_Init()  
    {  
        HAL_MspInit();  
    }  
  
    SystemClockConfig();  
  
    MX_PPP_Init()  
    {  
        HAL_PPP_Init()  
        {  
            HAL_PPP_MspInit();  
        }  
    }  
  
    HAL_PPP_Action();  
    while(1);  
}
```

Located in: main.c  
Called from: main.c

It performs the following operations:

- Initializes **PPP peripheral** based on STM32CubeMX configuration
  - Uses structures and dedicated initialization functions type `HAL_PPP_Init()`
  - Within those functions this is possible to tune a peripheral configuration



```
SystemInit();  
main()  
{  
    HAL_Init()  
    {  
        HAL_MspInit();  
    }  
  
    SystemClockConfig();  
  
    MX_PPP_Init()  
    {  
        HAL_PPP_Init()  
        {  
            HAL_PPP_MspInit();  
        }  
    }  
  
    HAL_PPP_Action();  
    while(1);  
}
```

# STM32CubeMX generated code code structure, main operations after the reset

Located in: `stm3214xx_hal_PPP.c`  
Called from: `main.c`

It performs the following operations:

- Initializes the **PPP peripheral mode** (according to parameters specified in the `PPP_InitTypeDef` structure) **and the associated handle**



```
SystemInit();  
main()  
{  
    HAL_Init()  
    {  
        HAL_MspInit();  
    }  
  
    SystemClockConfig();  
  
    MX_PPP_Init()  
    {  
        HAL_PPP_Init()  
        {  
            HAL_PPP_MspInit();  
        }  
    }  
  
    HAL_PPP_Action();  
    while(1);  
}
```

# STM32CubeMX generated code code structure, main operations after the reset

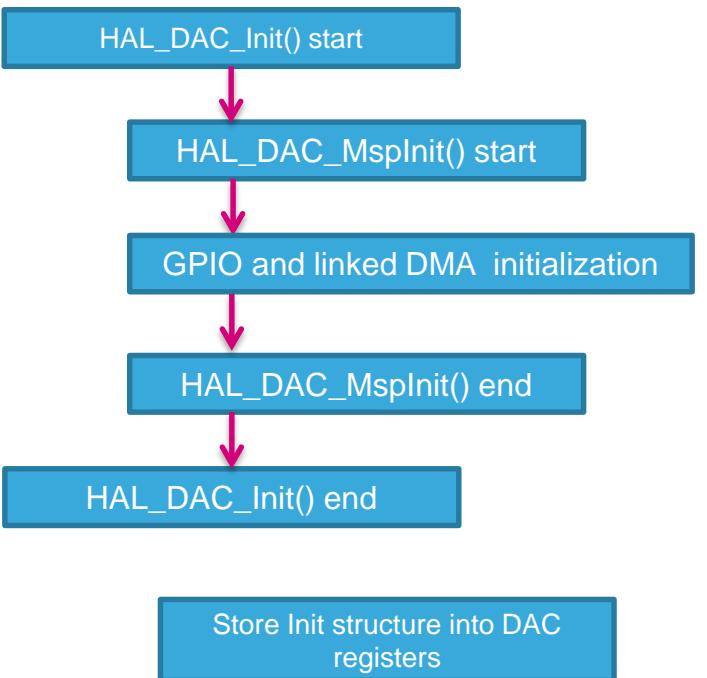
Located in: stm3214xx\_hal\_msp.c  
Called from: stm3214xx\_hal\_PPP.c

It performs the following operations:

- Configures **Clocks** related to PPP peripheral
- Configures **GPIO lines** assigned to PPP peripheral
- Configures **DMA channel** assigned to PPP peripheral  
(except source and destination address and number of the data to be transferred – this is done by HAL\_PPP\_Action() function)
- Configures **Interrupts** selected for PPP peripheral

# STM32CubeMX generated code peripherals initialization (DAC example)

- HAL\_DAC\_Init()  
function details



All HAL\_DAC\_Init() functions  
are calling the same function  
HAL\_DAC\_MsplInit()

Handler instance parameter  
is used to determine which  
DAC needs to be initialized

Initialize GPIO lines  
selected in  
STM32CubeMX

Initialize DMA channel  
selected in  
STM32CubeMX

```

void HAL_DAC_MsplInit(DAC_HandleTypeDef* hdac)
{
  GPIO_InitTypeDef GPIO_InitStruct;
  if(hdac->Instance==DAC)
  {
    /* USER CODE BEGIN DAC_MsplInit 0 */

    /* USER CODE END DAC_MsplInit 0 */
    /* Peripheral clock enable */
    __HAL_RCC_DAC_CLK_ENABLE();

    /**DAC GPIO Configuration
    PA4      -----> DAC_OUT1
    */
    GPIO_InitStruct.Pin = GPIO_PIN_4;
    GPIO_InitStruct.Mode = GPIO_MODE_ANALOG;
    GPIO_InitStruct.Pull = GPIO_NOPULL;
    HAL_GPIO_Init(GPIOA, &GPIO_InitStruct);

    /* Peripheral DMA init*/
    hdma_dac_ch1.Instance = DMA1_Channel2;
    hdma_dac_ch1.Init.Request = DMA_REQUEST_9;
    hdma_dac_ch1.Init.Direction = DMA_MEMORY_TO_PERIPH;
    hdma_dac_ch1.Init.PeriphInc = DMA_PINC_DISABLE;
    hdma_dac_ch1.Init.MemInc = DMA_MINC_ENABLE;
    hdma_dac_ch1.Init.PeriphDataAlignment = DMA_PDATAALIGN_HALFWORD;
    hdma_dac_ch1.Init.MemDataAlignment = DMA_MDATAALIGN_HALFWORD;
    hdma_dac_ch1.Init.Mode = DMA_CIRCULAR;
    hdma_dac_ch1.Init.Priority = DMA_PRIORITY_LOW;
    if (HAL_DMA_Init(&hdma_dac_ch1) != HAL_OK)
    {
      Error_Handler();
    }
    __HAL_LINKDMA(hdac,DMA_Handle1,hdma_dac_ch1);

    /* USER CODE BEGIN DAC_MsplInit 1 */

    /* USER CODE END DAC_MsplInit 1 */
  }
}
  
```



# STM32CubeMX generated code

## code structure, main operations after the reset

```
SystemInit();  
main()  
{  
    HAL_Init()  
    {  
        HAL_MspInit();  
    }  
  
    SystemClockConfig();  
  
    MX_PPP_Init()  
    {  
        HAL_PPP_Init()  
        {  
            HAL_PPP_MspInit();  
        }  
    }  
  
    HAL_PPP_Action();  
    while(1);  
}
```

Located in: main.c  
Called from: main.c

It performs the following operations:

- PPP **peripherals control** (i.e. Start, Stop, Calibration)
- **DMA configuration** if needed (buffer location, source and destination addresses, number of data to be transferred)



# STM32CubeMX generated code

## code structure, main operations after the reset - summary

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```
SystemInit();
```

```
main()
```

```
{
```

```
    HAL_Init()
```

```
{  
    HAL_MspInit();  
}
```

```
SystemClockConfig();
```

```
MX_PPP_Init()
```

```
{  
    HAL_PPP_Init()  
    {  
        HAL_PPP_MspInit();  
    }  
}
```

```
HAL_PPP_Action();
```

```
while(1);  
}
```

Operation	Function • called from • source location	Origin
<ul style="list-style-type: none"><li>Enable Floating Point Unit (FPU) inside the core</li><li>Reset the clock configuration to the default reset state</li><li>Disable all interrupts</li><li>Configure vector table location and its offset</li></ul>	<b>SystemInit()</b> <ul style="list-style-type: none"><li>startup_stm32xxxx.s</li><li>system_stm32xxxx.c</li></ul>	STM32CubeMX
<ul style="list-style-type: none"><li>Configure FLASH accelerator</li><li>Configure NVIC priority (group and sub-priorities split)</li><li>Configure SysTick for 1ms tick (based on HSI clock)</li><li>Initialization of low level hardware selected in STM32CubeMX (HAL_MspInit() function)</li></ul>	<b>HAL_Init()</b> <ul style="list-style-type: none"><li>main.c</li><li>stm32xxxx_hal.c</li></ul>	STM32CubeMX
<ul style="list-style-type: none"><li>Configure Interrupts priorities (for each peripheral selected in STM32CubeMX)</li></ul>	<b>HAL_MspInit()</b> <ul style="list-style-type: none"><li>stm32xxxx_hal_msp.c</li><li>stm32xxxx_hal_msp.c</li></ul>	STM32CubeMX
<ul style="list-style-type: none"><li>Configure System &amp; Buses clocks based on STM32CubeMX clock settings</li></ul>	<b>SystemClockConfig()</b> <ul style="list-style-type: none"><li>main.c</li><li>main.c</li></ul>	STM32CubeMX
<ul style="list-style-type: none"><li>Initialize PPP peripheral based on STM32CubeMX configuration:.PPP related peripheral configuration (GPIO lines, DMA channel) in function HAL_PPP_MspInit()</li></ul>	<b>MX_PPP_Init()</b> <ul style="list-style-type: none"><li>main.c</li><li>main.c or PPP.c</li></ul>	STM32CubeMX
<ul style="list-style-type: none"><li>Connect Clock to the peripheral</li><li>Configure GPIO lines</li><li>Configure DMA channels (based on STM32CubeMX settings)</li></ul>	<b>HAL_PPP_MspInit()</b> <ul style="list-style-type: none"><li>stm32xxxx_hal_msp.c</li><li>stm32xxxx_hal_msp.c</li></ul>	STM32CubeMX
<ul style="list-style-type: none"><li>Activate PPP peripherals control (i.e. Start, Stop, Calibration),</li><li>Configure DMA if needed (buffer location, source and destination addresses, number of data to be transferred)</li></ul>	<b>HAL_PPP_Action()</b> <ul style="list-style-type: none"><li>main.c</li><li>user_code.c</li></ul>	User



# STM32CubeMX generated code

## code structure - interrupts

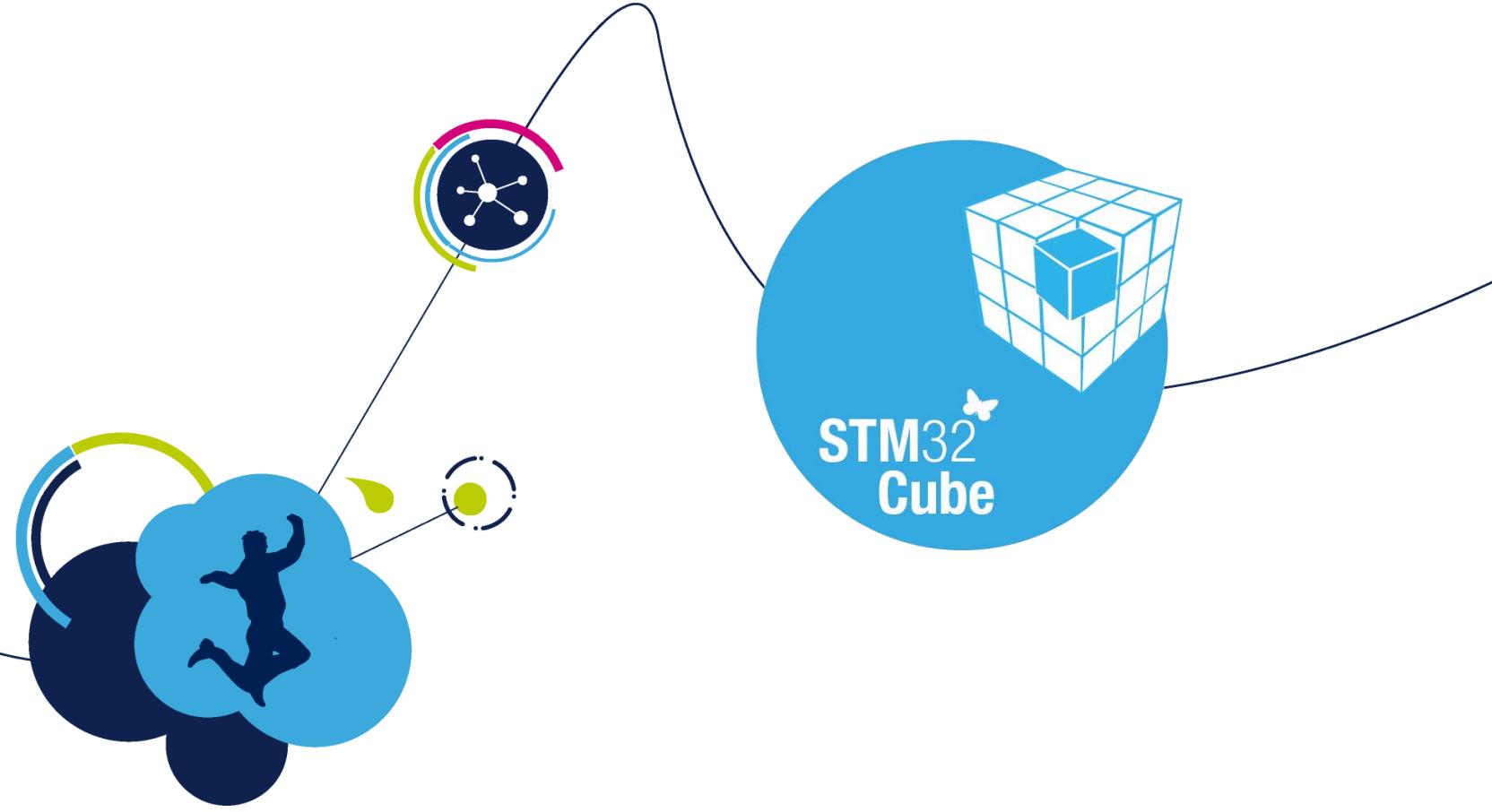
16

```
PPP_IRQHandler()  
{  
    HAL_PPP_Callback();  
}
```

operation	Function • called from • source location	Origin
<pre>• Check all possible flags and interrupt triggers • Clear all interrupts flags • Call proper callback functions assigned to the particular interrupt source/trigger</pre>	<b>PPP_IRQHandler()</b> • stm32xxxx_it.c • stm32xxxx_hal_ppp.c	STM32CubeMX
<pre>• Perform an action related to the specific interrupt.</pre>	<b>HAL_PPP_Callback()</b> • user_code.c	User

# HAL libraries

basic information





# HAL library

## function naming convention

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### HAL\_StatusTypeDef HAL\_PPP(Ex)\_Operation\_mode()

Return value:

- HAL\_OK
- HAL\_ERROR
- HAL\_BUSY
- HAL\_TIMEOUT
- void for simple peripherals (i.e. GPIO)

HAL prefix indicating type of the library (in contrary to Low Layer (LL))

PPP – peripheral name. If 'Ex' suffix is added it means that this particular function is related to current MCU family line and cannot be directly migrated to other STM32 lines

Type of the operation on the peripheral, like 'Start', 'Stop'

Mode of the operation:

- polling – no suffix
- Interrupt – suffix IT
- DMA – suffix DMA

See next slides for further details



**Hint:** to find proper function for the peripheral, please type **HAL\_PPP\_** and press **Ctrl+Space**

- Most of the configuration procedures are prepared and generated by STM32CubeMX based on user configuration
- After this process, within main() function, user should prepare series of the functions which would activate the selected peripherals in required mode:
  - Polling mode (function type `HAL_PPP_Action()`)
  - Interrupt mode (function type `HAL_PPP_Action_IT()`)
  - DMA mode (function type `HAL_PPP_Action_DMA()`)

# What have we learnt?

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- ✓ Understand the structure of the code generated by STM32CubeMX
  - ✓ Know the role of the library files
  - ✓ Know the role of the functions executed before main
  - ✓ Understand interrupt handling process

More information can be found in the following documents:

- **UM1860** - Getting started with STM32CubeL4 for STM32L4 Series, available on the web:  
[http://www.st.com/resource/en/user\\_manual/dm00157440.pdf](http://www.st.com/resource/en/user_manual/dm00157440.pdf)
- **UM1884** - Description of STM32L4 HAL and Low-layer drivers, available on the web:  
[http://www.st.com/resource/en/user\\_manual/dm00173145.pdf](http://www.st.com/resource/en/user_manual/dm00173145.pdf)
- Doxygen based html manual: **STM32L486xx\_User\_Manual.chm**, available within STM32L4xx Cube library in the path:  
  \STM32Cube\_FW\_L4\_V1.5.0\Drivers\STM32L4xx\_HAL\_Driver\

# Enjoy!



The image features a man in a purple tank top and red pants performing a dynamic breakdancing move, suspended in mid-air against a plain white background.

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The right side of the image contains a graphic for the STM32 L4 microcontroller. It includes a green circle with a white butterfly icon and the text "STM32 L4". To the right, there's a blue circular area containing a silhouette of a person dancing, a blue chip icon with "STM" on it, and a small green circle with a white smartphone icon. A wavy line connects the green circle to the blue area.